A NOTE ON SYSTEMS OF SUMMATION INEQUALITIES

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ABSTRACT

In this paper we discuss some systems of summation inequalities. We also discuss the under and over functions of systems of summation equations.

Keywords: Difference Equation, Summation Equation, Summation Inequality, Under and Over Function.

1. INTRODUCTION:

Agarwal [1], Kelley and Peterson [9] developed the theory of difference equations and difference inequalities. Some difference inequalities and comparison results are obtained by K. L. Bondar [2, 3]. Some summation and difference inequalities are obtained in K. L. Bondar [4, 5]. K. L. Bondar, V. C. Borkar, S. T. Patil [6, 7] and Dang H., Oppenheimer S.F.[8] obtained the existence and uniqueness results for difference equations. Some differential and integral inequalities are given in [10]. In this paper we discuss about systems of summation inequalities. We also discuss the under and over functions of systems of summation equations.

2. PRELIMINARY NOTES

Let $J = \{t_0, t_0 + 1... t_0 + a\}, t_0 \ge 0, t_0 \in R$, and E be an open subset of R^n , consider the difference equations with an initial condition,

$$\Delta u(t) = g(t, u(t)), u(t_0) = u_0$$
 (1)

where $u_0 \in E$, $u: J \to E$, $g: J \times E \to R^n$.

The function $\phi: J \to \mathbb{R}^n$ is said to be a solution of initial value problem (1), if it satisfies

$$\Delta \phi(t) = g(t, \phi(t)); \quad \phi(t_0) = u_0.$$

The initial value problem is equivalent to the problem

$$u(t) = u_0 + \sum_{s=t_0}^{t-1} g(s, u(s)).$$

By summation convention $\sum_{s=t_0}^{t_0-1} g(s, u(s)) = 0$ and so u(t) given above is the solution of (1).

3. MAIN RESULTS:

Theorem: 3.1 Assume that

(i) $K: J \times J \times R^n \to R^n$ and K(t, s, x) is nondecreasing in x for each fixed (t, s) and one of the inequalities

$$x(t) \le h(t) + \sum_{s=t_0}^{t-1} K(t, s, x(s)),$$
 (2)

$$y(t) \ge h(t) + \sum_{s=t_0}^{t-1} K(t, s, y(s))$$
 (3)

is strict where $x,y: J \to R^n$;

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(ii) $x(t_0) < y(t_0)$. Then

$$x(t) < y(t), \quad t \ge t_0. \tag{4}$$

Proof: Assume that the conclusion (4) is false. Then the set

$$Z = \bigcup_{i=1}^{n} [t \in [t_0, \infty) : x_i(t) \ge y_i(t)]$$

is nonempty. Let $t_1 = \inf Z$. By (ii), it is clear $t_1 > t_0$. Furthermore, since Z is closed, $t_1 \in Z$, and consequently there exists an index j such that

$$x_j(t_1) = y_j(t_1),$$

$$x_j(t) < y_j(t), t_0 \le t < t_1,$$

$$x_i(t) \le y_i(t), t_0 \le t < t_1, i \ne j.$$

Since K is monotone nondecreasing in x, it follows that

$$K_i(t_1, s, x(s)) \leq K_i(t_1, s, y(s)).$$

Hence, using (2) and (3), we arrive at the inequality

$$x_{j}(t_{1}) \leq h_{j}(t_{1}) + \sum_{s=t_{0}}^{t_{1}-1} K_{j}(t_{1}, s, x(s))$$

$$\leq h_{j}(t_{1}) + \sum_{s=t_{0}}^{t_{1}-1} K_{j}(t_{1}, s, y(s))$$

$$< y_{j}(t_{1}).$$

This is a contradiction to the fact that $x_i(t_1) = y_i(t_1)$. Hence Z is empty and the theorem is proved.

Let us now consider the summation operator defined by

$$K\phi = \sum_{s=t_0}^{t_1-1} K(t, s, \phi(s)).$$
 (5)

Definition: 3.2 We shall say that the operator K is monotone nondecreasing if, for any ϕ_1 , $\phi_2: J \to \mathbb{R}^n$ such that, for any $t_1 > t_0$,

$$\phi_1(t) < \phi_2(t), t_0 \le t < t_1$$

implies

$$K\phi_1(t_l) \leq K\phi_2(t_l).$$

Theorem: 3.3 Let the operator K defined by (5) be monotone nondecreasing. Suppose further that, for $t > t_0$,

$$x - Kx < y - Ky, \tag{6}$$

where $x, y: J \times \mathbb{R}^n$. Then $x(t_0) < y(t_0)$ implies

$$x(t) < y(t), t \geq t_0$$
.

Proof: Assume that the conclusion of theorem is false. Then set

$$Z = \bigcup_{i=1}^{n} [t \in [t_0, \infty) : x_i(t) \ge y_i(t)]$$

is nonempty. Let $t_1 = \inf Z$. By (ii), it is clear that $t_1 > t_0$. Furthermore, since Z is closed, $t_1 \in Z$, and consequently there exists an index j such that

$$x_i(t_1) = y_i(t_1),$$

$$x_i(t) < y_i(t), t_0 \le t < t_1,$$

$$x_i(t) \leq y_i(t), t_0 \leq t < t_1, i \neq j.$$

Since *K* is monotone nondecreasing in *x* and using above inequalities, it follows that,

$$K_i x_i(t_1) \le K_i y_i(t_1). \tag{7}$$

As a result, (6) and (7) yield

$$x_{j}(t_{1}) = x_{j}(t_{1}) - K_{j}x_{j}(t_{1}) + K_{j}x_{j}(t_{1})$$

$$< y_{j}(t_{1}) - K_{j}y_{j}(t_{1}) + K_{j}y_{j}(t_{1})$$

$$\leq y_{i}(t_{1}).$$

This contradicts the fact that, at $t = t_1$, $x_i(t_1) = y_i(t_1)$, and hence the proof is complete.

Definition: 3.4 A function $u: J \to \mathbb{R}^n$ is said to be an under function of the system of summation equation

$$x = j + Kx \tag{8}$$

if it satisfies the inequality

$$u < h + Ku$$
.

Similarly u is said to be an over function of (8) if verifies the system of inequality

$$u > h + Ku$$
,

whereas if u satisfies equation (8), it is said to be a solution of (8).

Theorem: 3.5 Let the operator K defined by (5) be monotone nondecreasing. Suppose that x, y, z: $J \to R^n$ be an under function, a solution and an over function of (8), respectively on J. Then

$$x(t_0) < y(t_0) < z(t_0)$$

implies

$$x(t) < y(t) < z(t), \quad t \ge t_0.$$

Proof: As x(t) is an under function and y(t) is a solution of (8) respectively, we have

$$x(t) < h(t) + \sum_{s=t_0}^{t-1} K(t, s, x(s))$$
 and

$$y(t) = h(t) + \sum_{s=t_0}^{t-1} K(t, s, y(s)).$$

Also if $x(t_0) < y(t_0)$, they by Theorem 3.1, we have

$$x(t) < y(t), \quad t \ge t_0$$
.

Similarly using definition of solution, an over function of (8) and by Theorem 3.1 again we obtain

$$y(t) < z(t), t \ge t_0$$
.

Hence

$$x(t) < y(t) < z(t), \quad t \ge t_0.$$

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